Gradient Projection Algorithms for Arbitrary Rotation Criteria in Factor Analysis

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The factor analysis model

X = Λξ + U

where

X are multivariate normal random vectors Λ are factor loadings ξ are common factors U are error of measurement

> Exploratory factor analysis model: no prior values for factor loadings

Applied in psychology, economics, chemistry, survey data, etc.

The problem

A well known issue in exploratory factor analysis is that the solution is unique only up to a rotation of the factor loadings

In the orthogonal case $\Lambda = AT$ where A is an initial solution, and is T any orthogonal matrix.

In the oblique case $\Lambda = A(T')^{-1}$ where T is any normal <u>matrix</u>.

The rotation problem is to find T such that A is simple and looks good. This is usually done by optimizing some criterion.

Criteria

Let Q be a smooth criterion function that measures the complexity of Λ .

Orthogonal: Minimize $f(T) = Q(\Lambda) = Q(AT)$ over all orthogonal matrices.

Oblique: Minimize $f(T) = Q(\Lambda) = Q(A(T')^{-1})$ over all normal matrices.

Gradient projection for factor analysis

O. Choose initial **T**.

1. Compute G = df/dT, gradient G of f at T, the matrix of partial derivatives.

2. Replace T by its projection of T – α G onto the manifold of permissible matrices.

3. Goto step 1 or stop.

Function values are minimized

The algorithm visualized



manifold of permissible matrices

Algorithm properties

Can be shown to decrease value of f at every iteration, with appropriate α . A partial step modification is used to guarantee this. How to compute G In step 1, G = df/dT is needed Let $G_q = dQ/dA$ is gradient of Q at A. Because $G = A'G_q$ (orthogonal) $G = -(A'G_qT^{-1})'$ (oblique) all that required to compute G is G_q .

Mathematical definitions

Frobenius norm: (X,Y) = tr(X'Y)Elementwise product: X·Y and $X^2 = X \cdot X$

Example: Quartimax (orthogonal only) $Q(\Lambda) = -(1/4) \sum_{i} \sum_{r} \lambda_{ir}^{4} = -(\Lambda^{2}, \Lambda^{2})/4$ <u>Note: Minus because of minimization.</u>

 $dQ = -(\Lambda \cdot d\Lambda, \Lambda^2)/2 - (\Lambda^2, \Lambda \cdot d\Lambda)/2$ $= -(\Lambda \cdot d\Lambda, \Lambda^2) = -(\Lambda^3, d\Lambda)$ Thus, $G_a = -\Lambda^3$

Currently implemented

Orthogonal

Crawford-Ferguson (quartimax, varimax, equamax, parsimax, factor parsimony), orthomax (quartimax, varimax, equamax), invariant pattern simplicity, minimum entropy, oblimax, simplimax, tandem criterion I and II, target rotation.

Oblique

Oblimin (quartimin, biquartimin), Crawford-Ferguson, geomin, invariant pattern simplicity, simplimax, target rotation.

How to obtain the algorithms?

Routines can be downloaded free of charge from http://www.stat.ucla.edu/research/gpa

SAS PROC IML SPSS matrix language Splus R Matlab (Stata)

Alternatives

Pairwise rotation. Implemented in CEFA (Browne et al., 1998) http://quantrm2.psy.ohio-state.edu/browne

Browne (2001). An overview of analytic rotation procedures in exploratory factor analysis. Multivariate Behavioral Research, 36, 111-150.

Questions?

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